



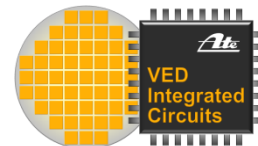
Mastering Unexpected Situations Safely



Using SystemC Models for pre-silicon development of an ATE Test Suite

COSIDE[®] User Group Meeting 2015

Agenda



1 Continental Business Unit Vehicle Dynamics

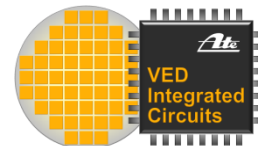
2 Motivation

3 System to be Modelled

4 Results & Conclusion

Continental Corporation

Five Strong Divisions



Chassis & Safety

Vehicle Dynamics

Hydraulic Brake Systems

Passive Safety & Sensorics

Advanced Driver Assistance
Systems (ADAS)

Powertrain

Engine Systems

Transmission

Hybrid Electric Vehicle

Sensors & Actuators

Fuel & Exhaust Management

Interior

Instrumentation & Driver HMI

Infotainment & Connectivity

Intelligent Transportation
Systems

Body & Security

Commercial Vehicles &
Aftermarket

Tires

PLT, Original Equipment

PLT, Repl. Business, EMEA

PLT, Repl. Business,
The Americas

PLT, Repl. Business,
Asia Pacific

Commercial Vehicle Tires

Two Wheel Tires

ContiTech

Air Spring Systems

Benecke-Kaliko Group

Compounding Technology

Conveyor Belt Group

Elastomer Coatings

Fluid Technology

Power Transmission Group

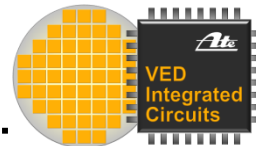
Vibration Control

PLT – Passenger and Light Truck Tires



The Basics

If a car assists you or drives you automatically, it has to ...



Sense



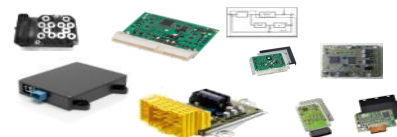
...sense its environment
and vehicle's current state...



Plan



...plan its actions...



Act

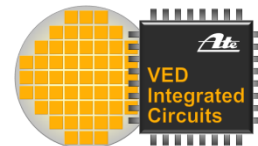


...act using the car's
actuators and control systems.



Chassis & Safety Division

Business Units



Vehicle Dynamics

- › Hydraulic Electronic Control Units (HECU)
 - › ABS
 - › ESC
- › Software functions
 - › Traction Control
 - › Adaptive cruise control
 - › Regenerative brake system
 - › Active front steering
 - › Hill start assist
 - › Hydraulic brake assist
 - › Trailer stability assist
- › Chassis electronics
- › Suspension systems



Hydraulic Brake Systems

- › Calipers
- › Drum brakes
- › Brake hoses
- › Boosters
- › Tandem master cylinders
- › Electric parking brakes
- › Pedal modules
- › Brake pressure regulators
- › Washer systems



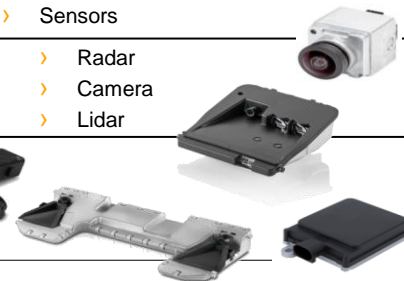
Passive Safety & Sensorics

- › Integrated vehicle safety development, safety testing & validation
- › Airbag control units / safety (domain) control units
- › Crash sensors
- › Inertial measurement units
- › Chassis and driver intention sensors
- › Battery and energy monitoring sensors
- › Electronic components (1st tier customer)
- › Wheel, engine and transmission speed sensors
- › Accelerator Force Feedback Pedal (AFFP®)
- › V2X systems

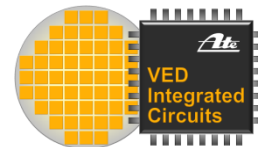


Advanced Driver Assistance Systems

- › Functions
 - › Adaptive cruise control
 - › Emergency brake assist
 - › Lane departure warning
 - › Lane keeping support
 - › Blind spot detection
 - › Traffic sign assist
 - › Intelligent head lamp control
 - › Rear cross traffic alert
 - › Surround View
- › Sensors
 - › Radar
 - › Camera
 - › Lidar



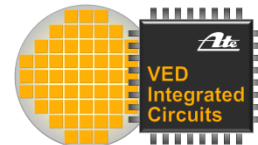
Components of a Hydraulic Electronic Control Unit



- › Motor
- › Valve block
- › Electronic Control Unit
 - › Microcontroller
 - › Mixed-Signal IC (PCU)



Agenda



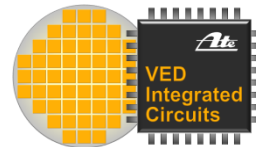
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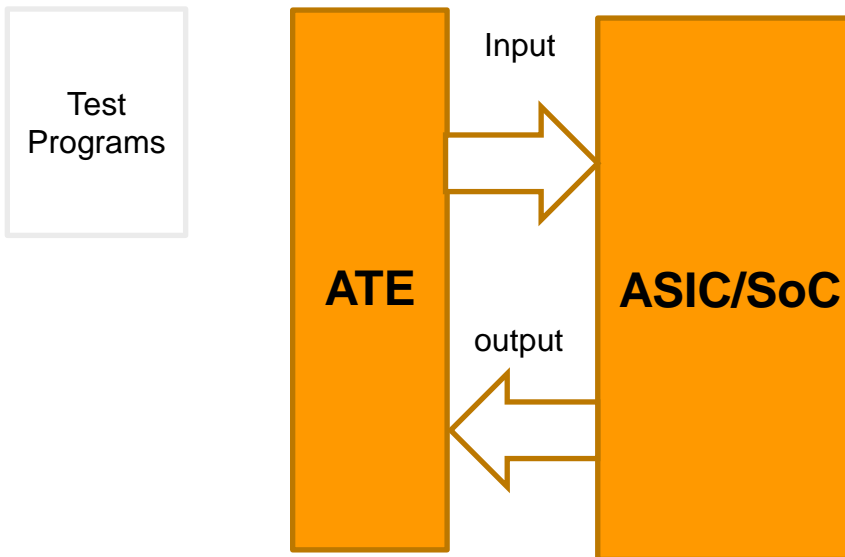
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4 Results & Conclusion

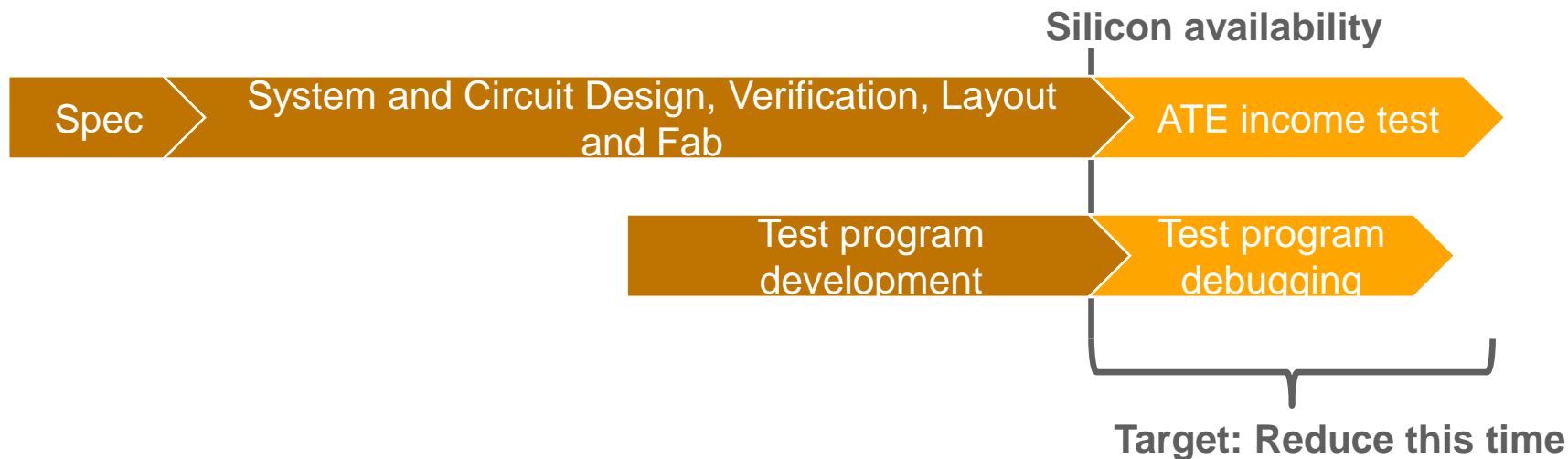
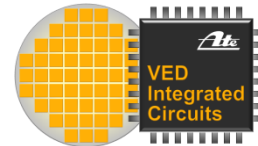
Automated Test Equipment



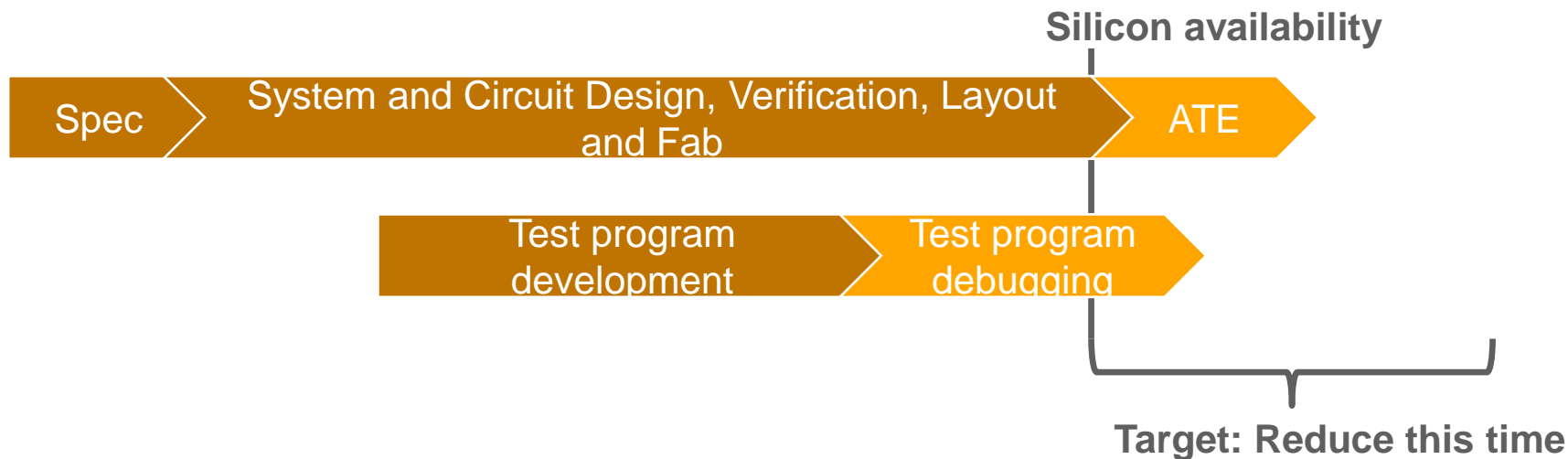
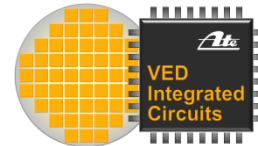
- › First mixed-signal IC samples have to run through a series of tests to show that they meet the requirements.
- › These tests are performed with the help of an Automated Test Equipment (ATE)
- › An ATE system contains instruments that can drive or measure the individual pins of the IC under test
- › How to operate these instruments is controlled by test programs which in our case are written in C language



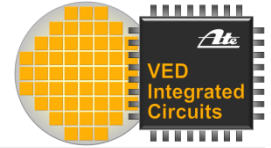
Bottleneck: Time for Test Program Development



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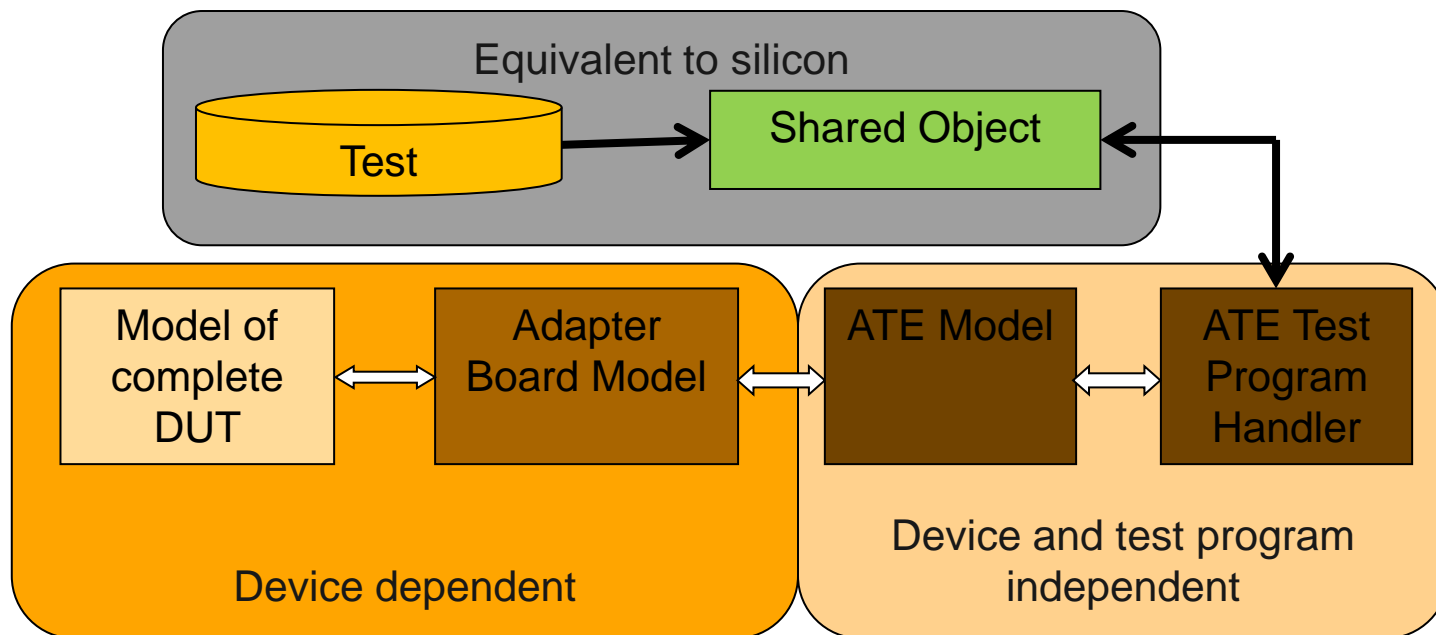
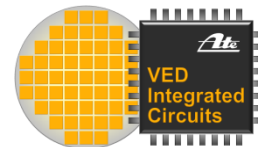
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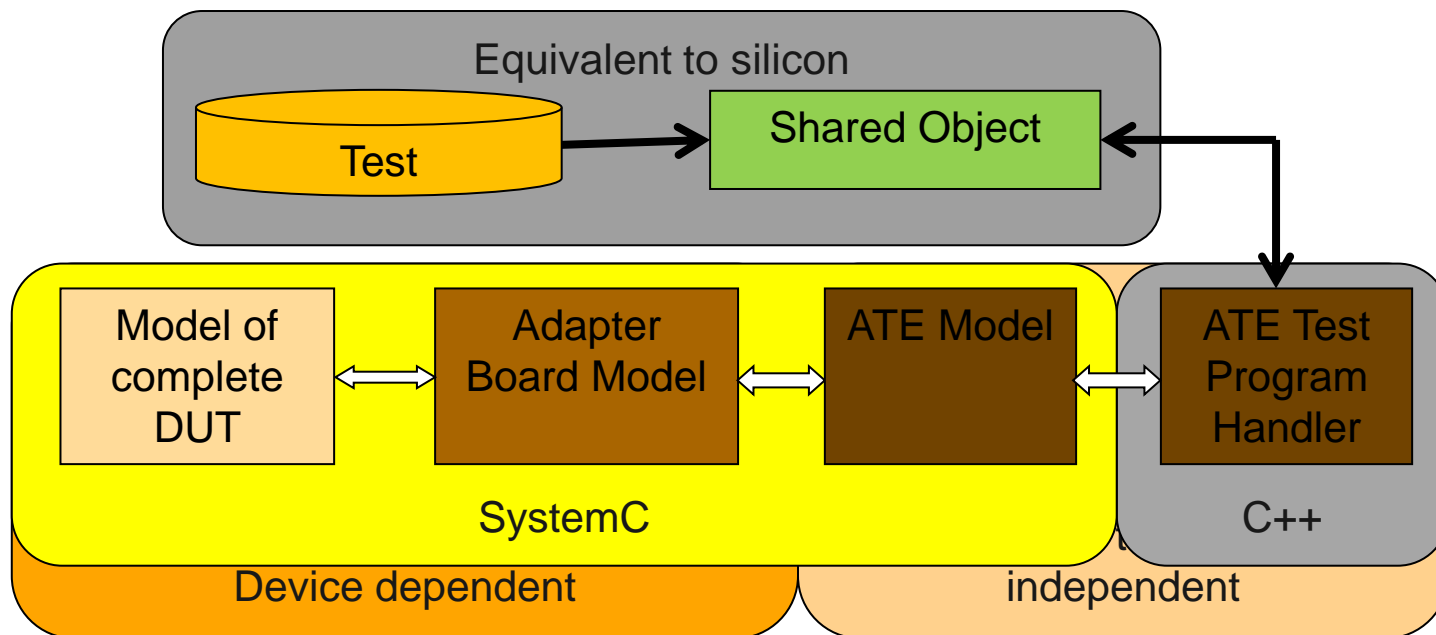
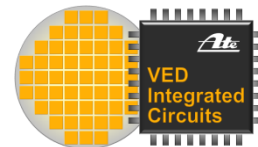
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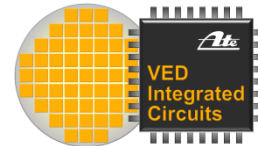
VirtualATE model



VirtualATE model



Device dependent models



- › Device Under Test

- › Hierarchical model of complete IC

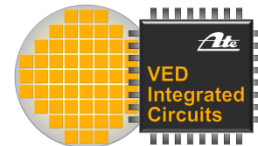
- › Adapter board

- › Connection between ATE model and DUT model
 - › Conversion of ATE model data types (real) to DUT data types (e.g. electrical, logic)
 - › ~ 1 module for each pin of DUT
 - › External circuitry



Example for DUT

Agenda



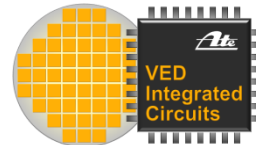
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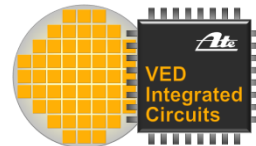
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Results



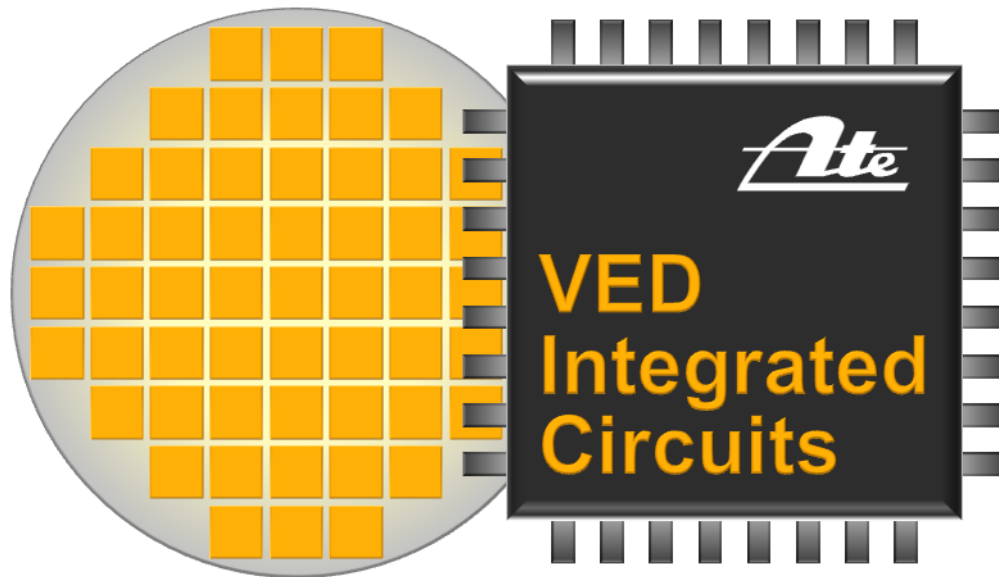
- › Using VirtualATE the test program quality can be significantly increased before silicon availability
- › Examples for errors detected:
 - › Wrong address used in SPI transfer
 - › Wrong range expected for result
 - › Result stored in wrong location
 - › Saturation of ADC not handled correctly
 - › Endless loops due to not changing condition
 - › Mixing voltages and currents
 - › Missing initialization
 - › Wrong ADC range

Conclusion



- › VirtualATE helps to significantly improve the test program quality before silicon availability
- › A model of board and DUT is required to achieve this benefit
- › Complexity of board and DUT can only be handled with COSIDE® as IDE for SystemC-AMS

Thank you
for your attention!



ASIC solutions for Vehicle Dynamics

Safe and Dynamic Driving towards Vision Zero

SensePlanAct

Chassis & Safety

Continental 

