

07.12.2023 | 10th COSIDE User Group Meeting

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Motivation

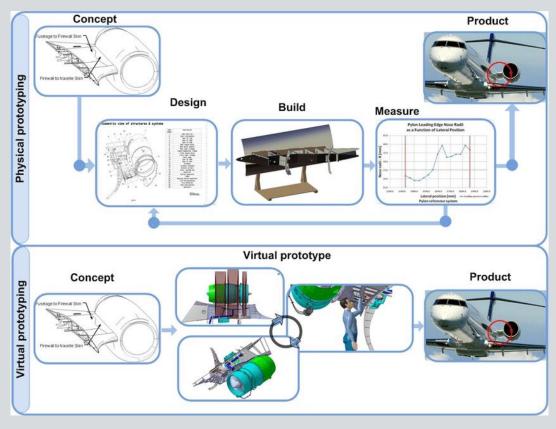
- Increasing complex electrical and electronic components in automotives demands highperformance and data processing computing nodes
- Automotive OEMs must consider entire system together for testing & verification instead of testing only individual elements



Virtual Prototype (VP)

- Virtual Prototype (hardware replica) is used
 - For specification, implementation, verification
 - Reduces costs
 - Helps develop the right system & develop the system correctly (detecting errors early)
- Reduces bottleneck in overall system simulation time

 Create technical base for exchange of scenario along the Electronic design chain (e.g., test and application scenarios)



PASVER Project Goals

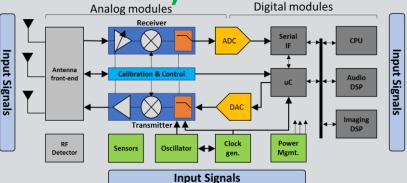


Accelerate simulations in <u>mixed-signal VPs</u> using <u>checkpointing</u> technique

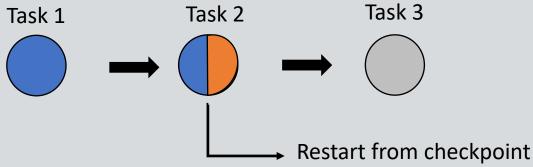
<u>SystemC AMS</u> – development of checkpointing APIS for heterogeneous virtual

prototype (analog + digital + software)

Analog modules



• Checkpointing - technique used to store and restore system state





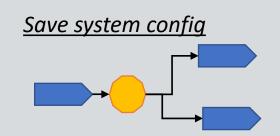
Checkpoint Applications

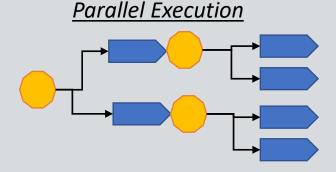
• Checkpoint saves the system config (e.g., saves time in boot sequence, sensor initialization, etc.,)

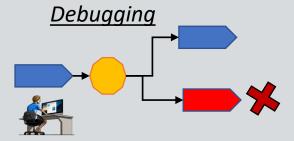
 Checkpoint can be used as a basis and inputs can be varied for parallel execution of scenarios

Checkpoint can be used to analyze the cause of the error

For VP's checkpoints shall include (memory state, processor state, peripheral, active transactions, etc.,)

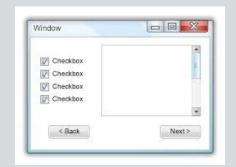




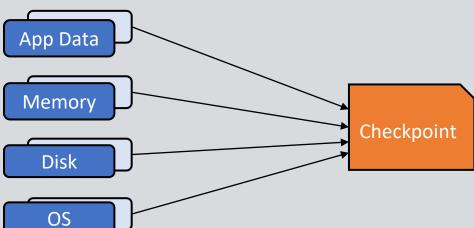


Challenges in Checkpointing

- Manual Checkpointing (variant 1)
 - requires standardization enabled interfaces (API)

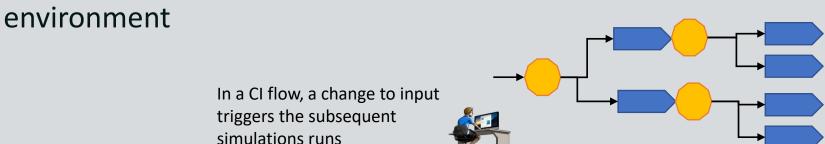


- Checkpointing by storing process context (variant -2)
 - requires efficient storage mechanism
 - Checkpoints cannot be transferred to other System
 - Modification of Checkpoints hardly possible

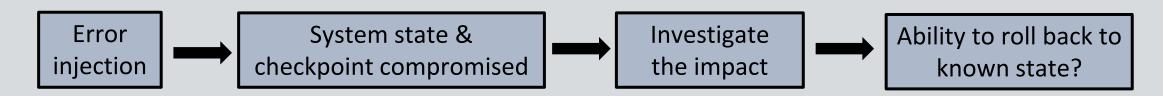


Challenges in CI Integration & Debugging

System modification in VP for simulating in a Continuous Integration (CI)



• Distribution of checkpoints in the system for debugging failed simulation



Challenges in Checkpoint metrics

Metrics to assess checkpoints

 Algorithms to analyze checkpoints and simulation data to evaluate the parallelizable simulation runs

• Remove redundant scenarios to improve simulation time

Roadmap for Checkpointing Implementation



- Development of a methodology to implement checkpointing in mixed-signal systems
- Analyze the performance of checkpointing methods
- Describe necessary changes in VP with checkpointing to implement it in a CI system
- Examine effect of error injection and system's ability to recover
- Explore metrics to compare checkpoints
- Investigate possible algorithms to eliminate redundant test scenarios and accelerate simulation
- API for Checkpointing
 - Give API to Accellera as long term goal

Food for Thought

- CCI parameters essentially provide the core mechanism needed to represent state outside of a running model
 - Host-independent expression of data values with a name
 - Name-value mappings and a type system for values
- · Still need to deal with kernel, structure, and making sure all state gets saved and restored
 - Restoring SystemC threads
- Store Solver States for SystemC AMS
- Models might have to be adapted to support checkpointing, in particular:
 - Keep model state explicit and separate from implementation
 - Deal with thread positions
 - Deal with in-place state changes
 - Avoid keeping things on the stack



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