

Product modeling @ SC Villach

Using SystemC and Coside to enable effective IC development and customer support

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confidential

Agenda

1

Introduction on Magnetic Sensors & Product Modeling

2

Some examples from the last two years

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Why we do like Coside?

4

Conclusions

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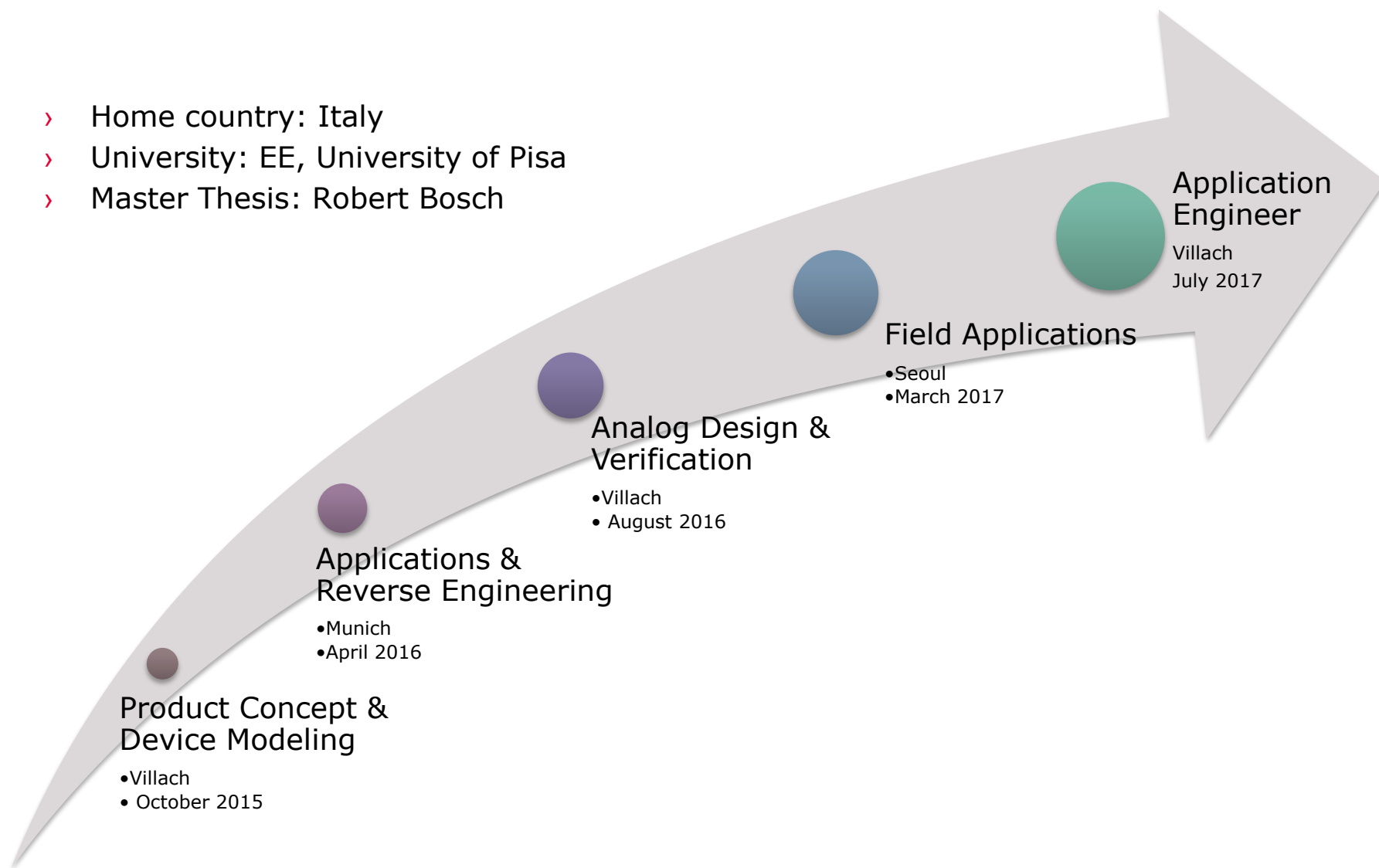
Why we do like Coside?

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Conclusions

24 months @ Sense and Control ATV

- > Home country: Italy
- > University: EE, University of Pisa
- > Master Thesis: Robert Bosch



Infineon Technologies Austria AG (Villach)



Infineon Villach divisions and products



Automotive (ATV)

- Power Semi-conductors
- Power ICs
- Microcontrollers
- Sensors
- Electric Drivetrain



Industrial Power Control (IPC)

- IGBT Modules
- IGBT (Chips & Discretes)
- Driver ICs and boards
- Module Systems



Power Management & Multimarket (PMM)

- Power Discretes & Driver ICs
- Power ICs
- ASICs
- RF & Protection Devices
- Silicon MEMS-Microphones

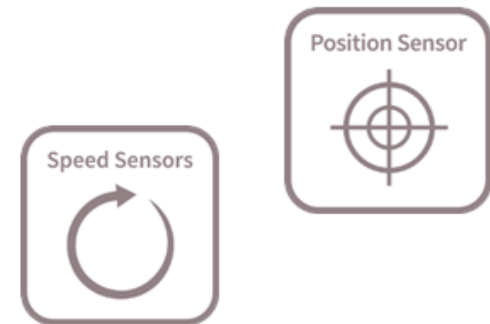
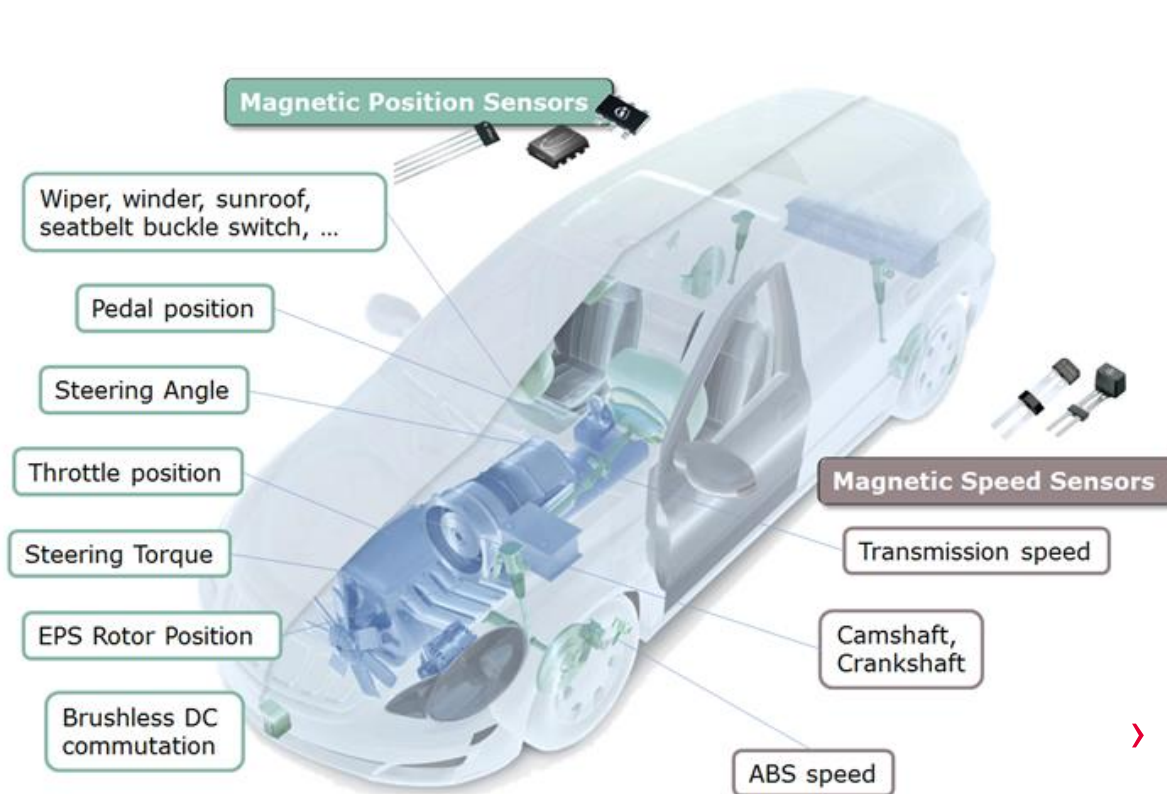


Chip Card & Security (CCS)

- Payment
- Communication
- Transport, Access & Object ID
- Government ID
- Platform Security
- Entertainment

Magnetic sensors in automotive market

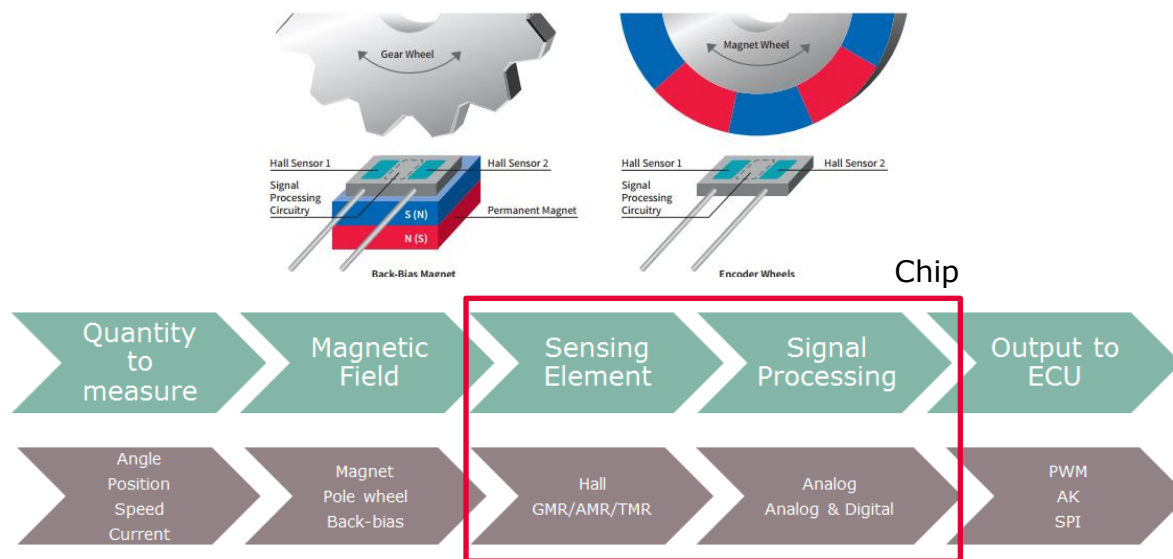
- › Application: contactless measurement of mechanical quantities



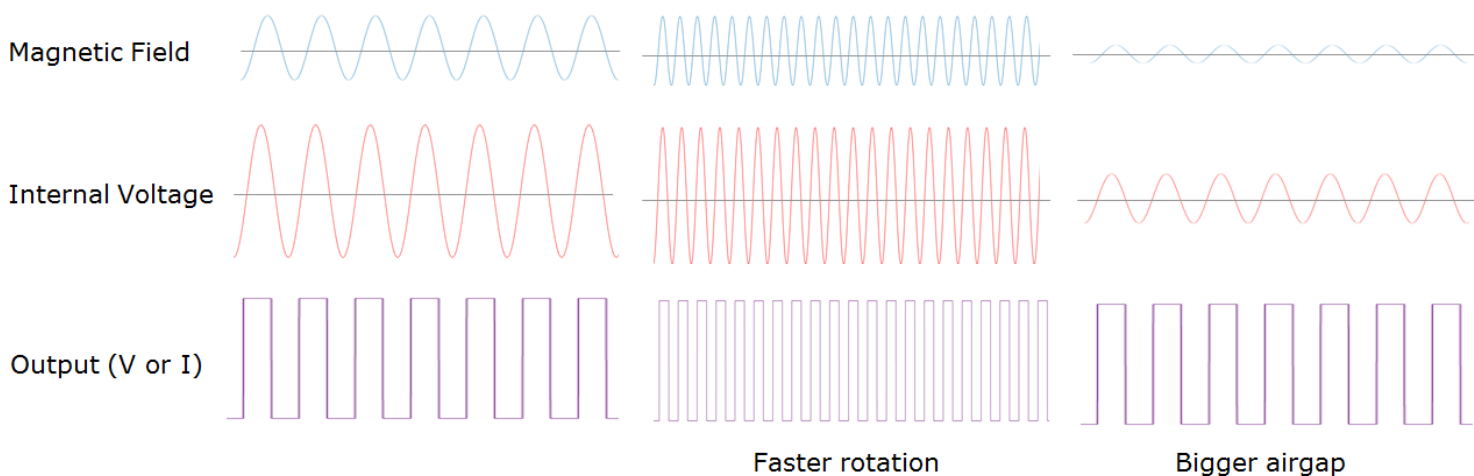
› Benefits

- › Contactless
- › Robust
- › Standard material housing
- › Low-cost

Magnetic sensors working principle



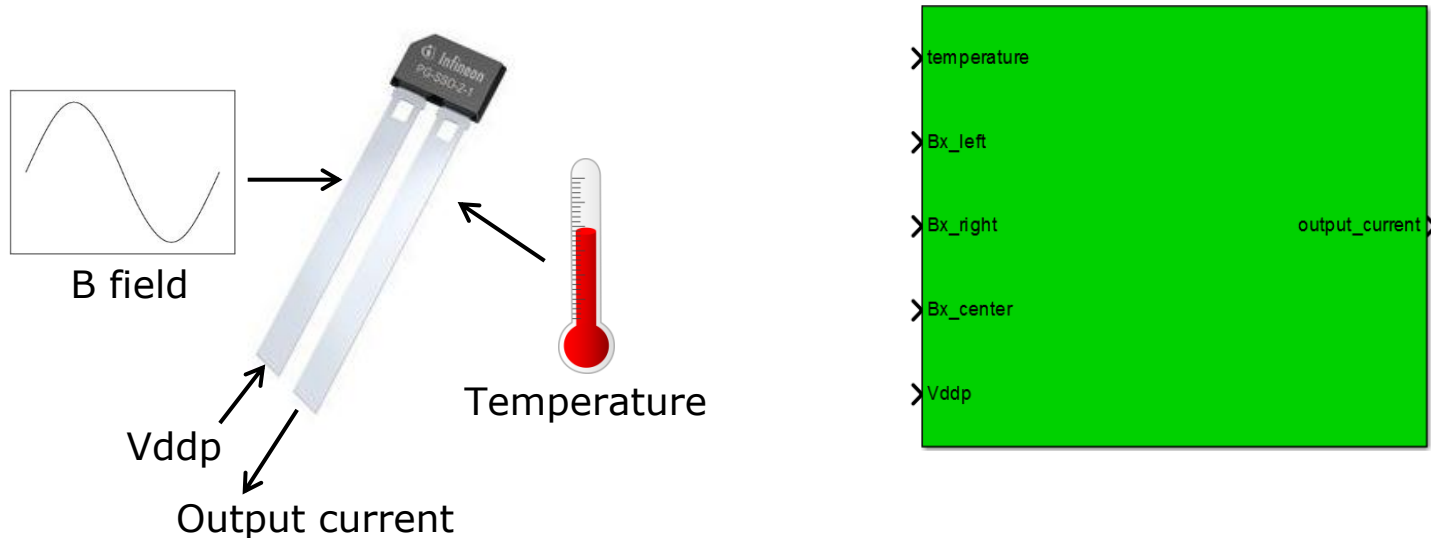
› Example: speed sensors



What is a product model?

› Definition of **model**:

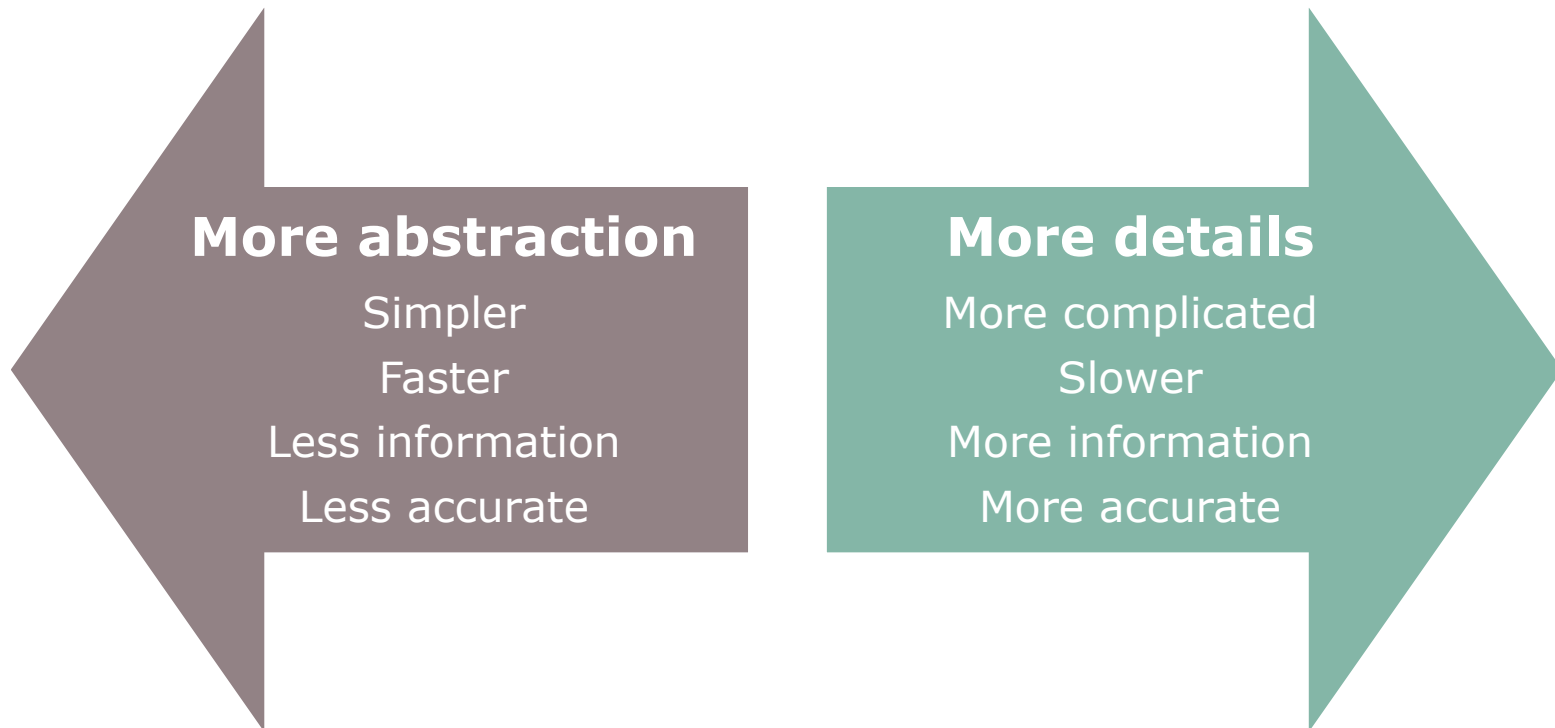
"Graphical, mathematical, physical, or verbal representation or simplified version of a concept, phenomenon, relationship, structure, system, or an aspect of the real world"



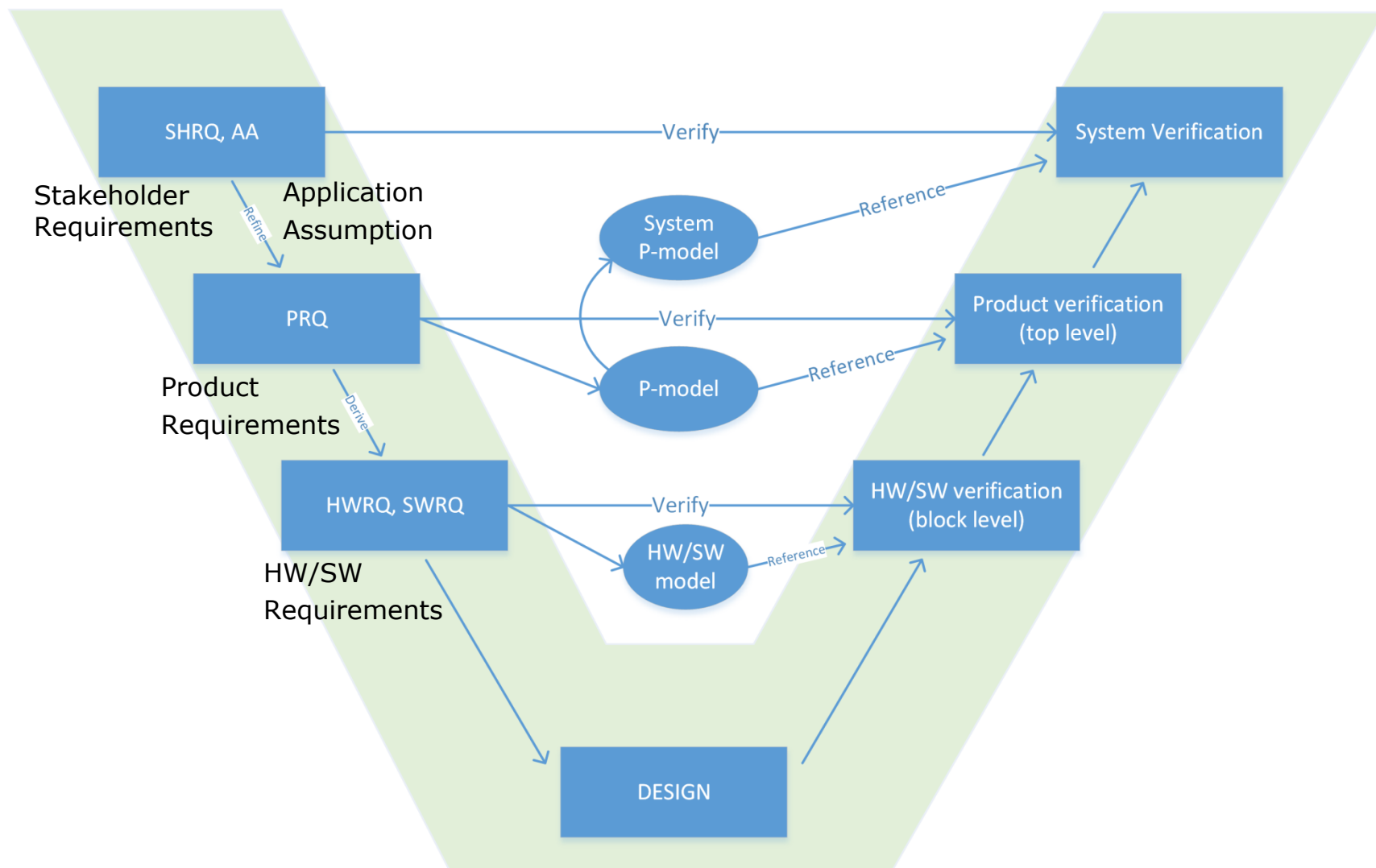
› Read more: <http://www.businessdictionary.com/definition/model.html>

What does a model include?

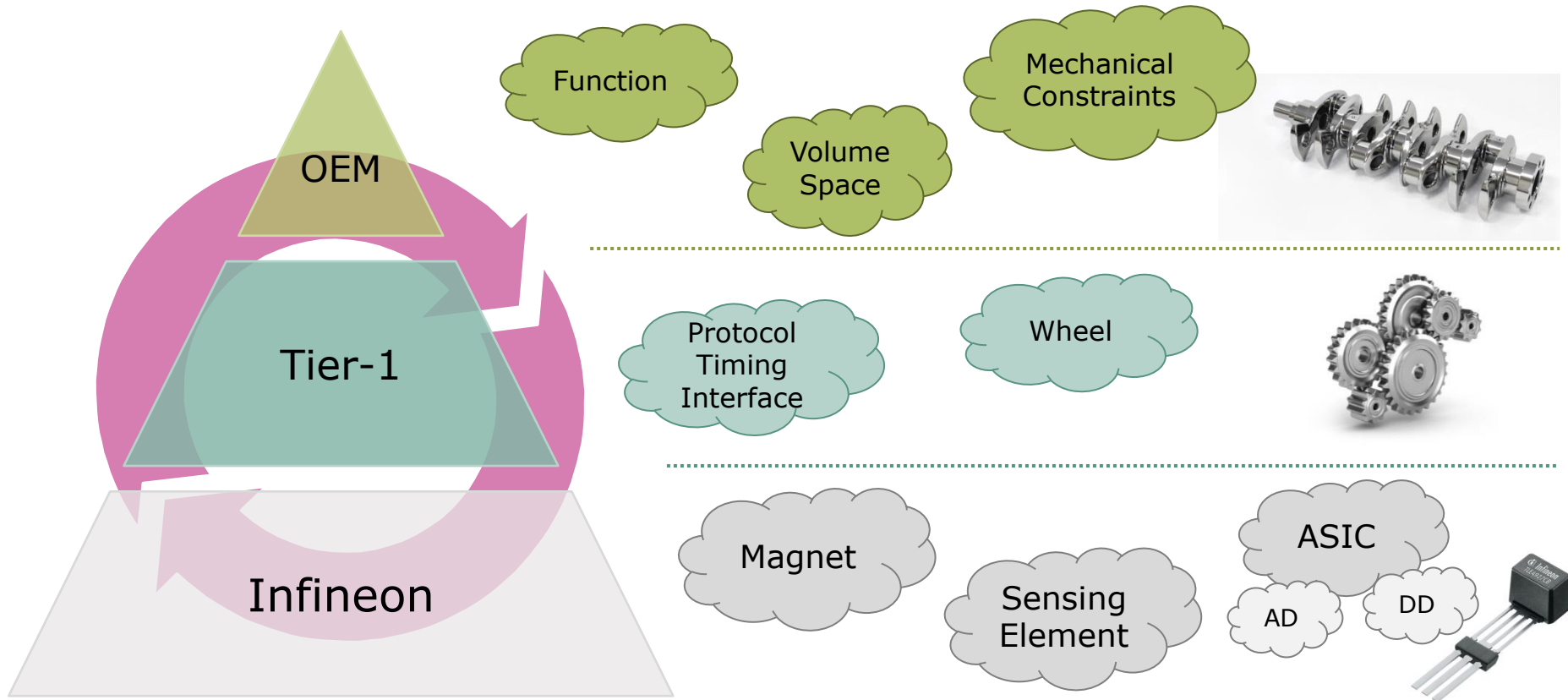
- › *"Since most objects and phenomenon are very complicated (have numerous parts) and much too complex (parts have dense interconnections) to be comprehended in their entirety, **a model contains only those features that are of primary importance to the model maker's purpose**"*
- › Read more: <http://www.businessdictionary.com/definition/model.html>



V-model methodology



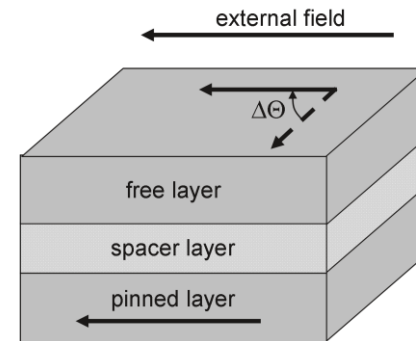
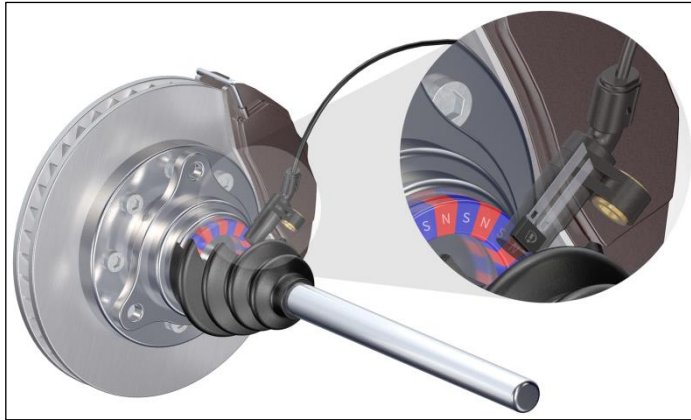
Modeling driven by P2S strategy



- › Goal: increase our contribution on the system definition, which enables us to offer optimized sensor solutions in terms of performance, value and costs

Combined simulation flow

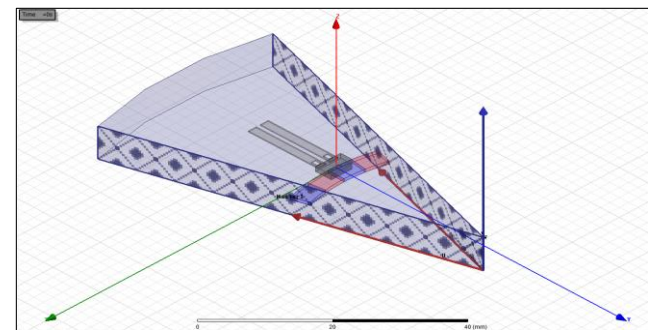
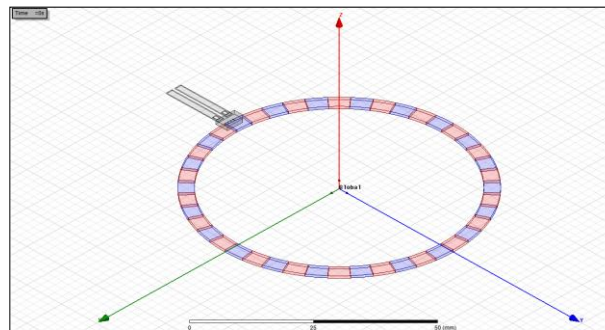
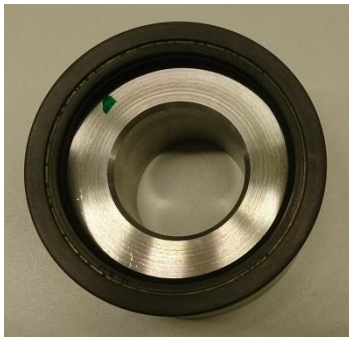
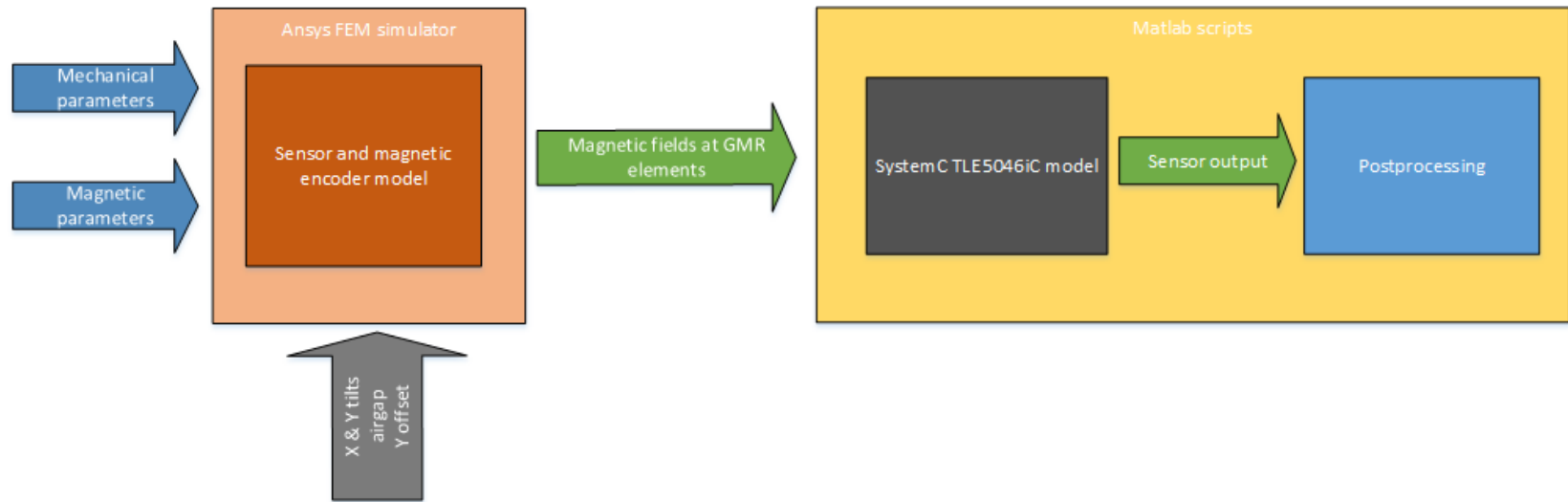
Example from DVCon Europe 2017



- › Duty cycle and jitter performance of GMR based sensors may be degraded if B_y component of the encoder wheel field is too big
- › Due to tilt and offset in assembly the B_y in-plane component of the field may increase
- › It is useful to investigate and predict such phenomena via measurements and simulations (faster, cheaper, more flexible)

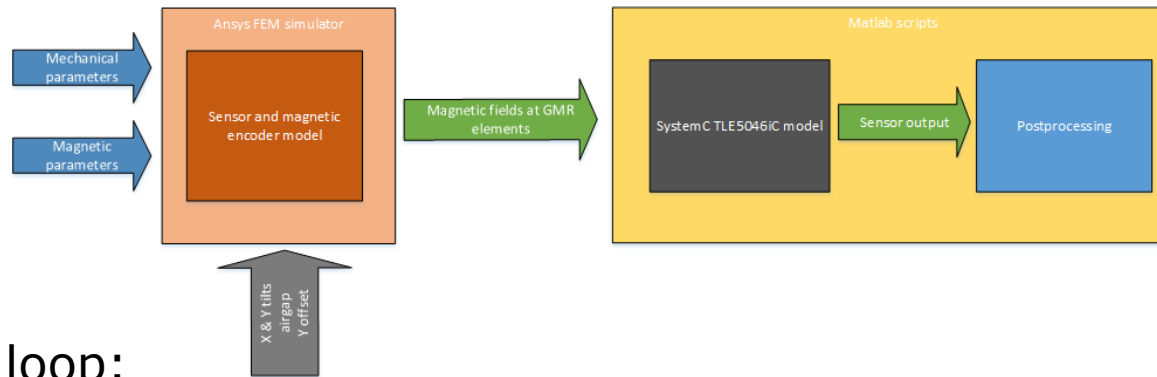
Simulation flow – FEM

Example from DVCon Europe 2017



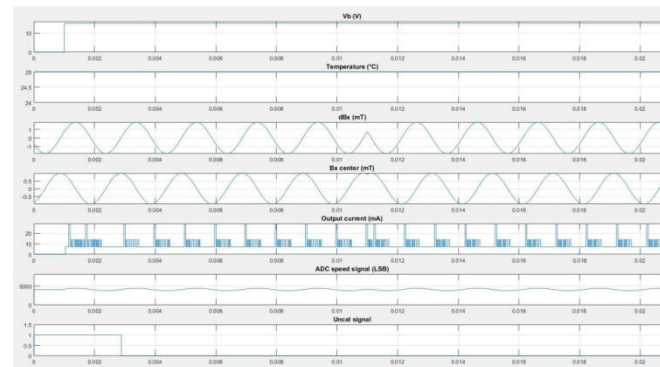
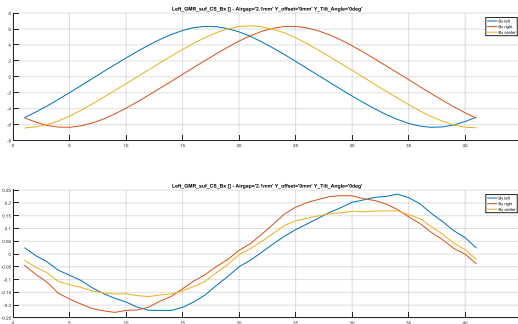
Simulation flow – SystemC + Matlab

Example from DVCon Europe 2017



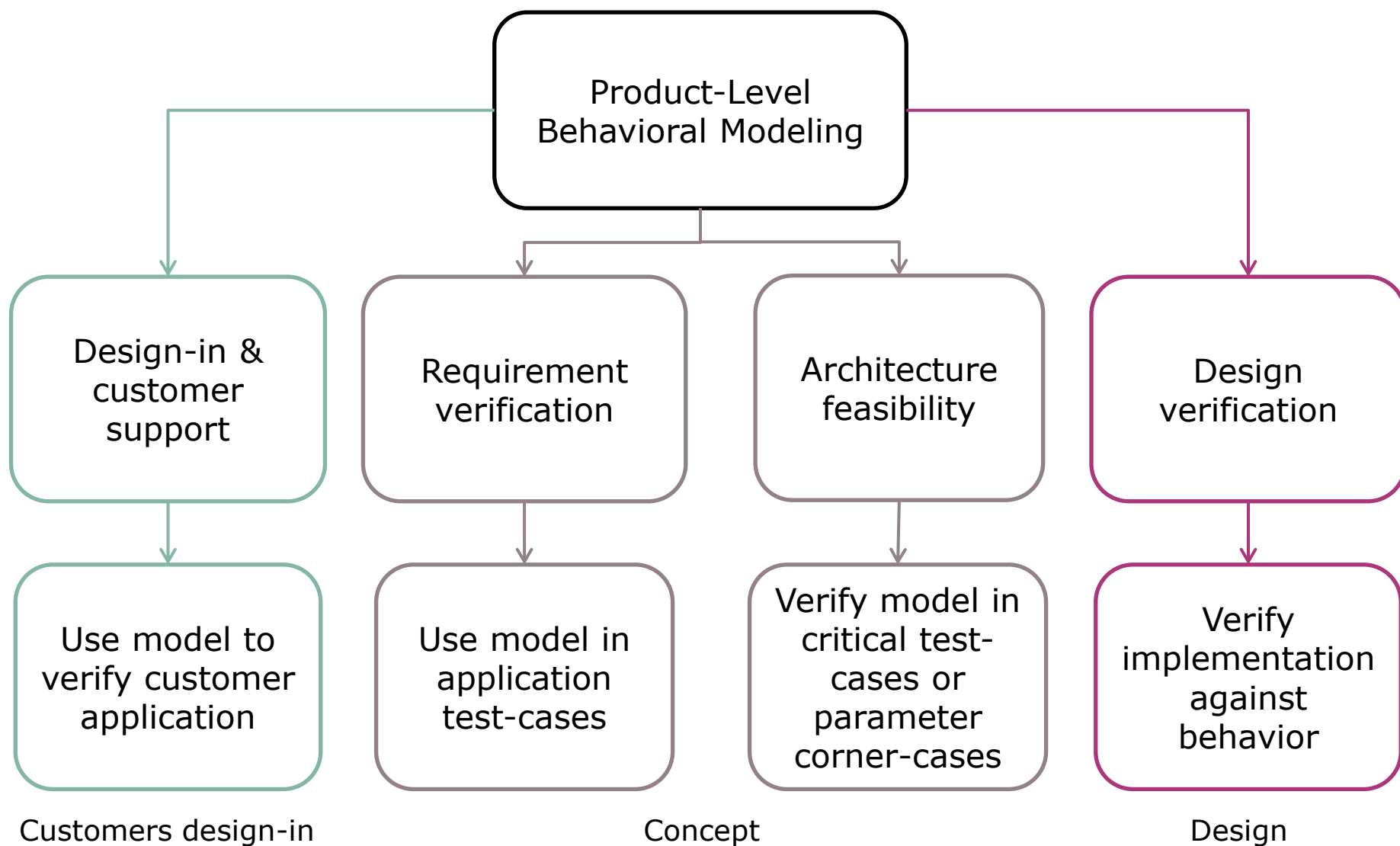
› Repeat in a loop:

1. Read the results from Ansys FEM simulations
2. Post-process the results in a SystemC friendly format
3. Run the SystemC simulation
4. Perform automatic pass/fail tests on the simulation output



PASS ☒
FAIL ☐

Product modeling use cases



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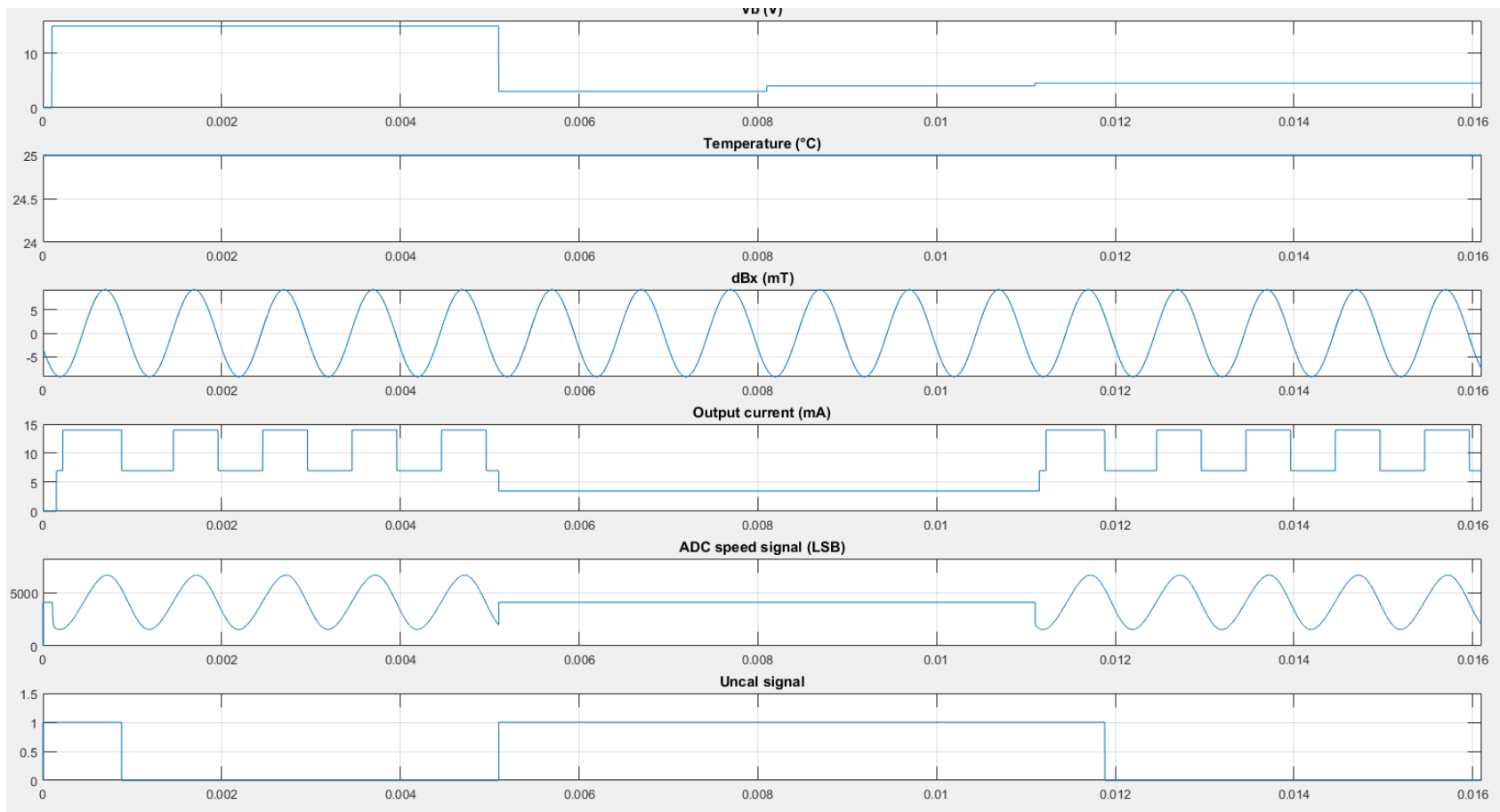
Conclusions

TLE5045iC/46iC models

Customer questions answered via simulations



› Ex 1: Undervoltage behavior of TLE5045iC

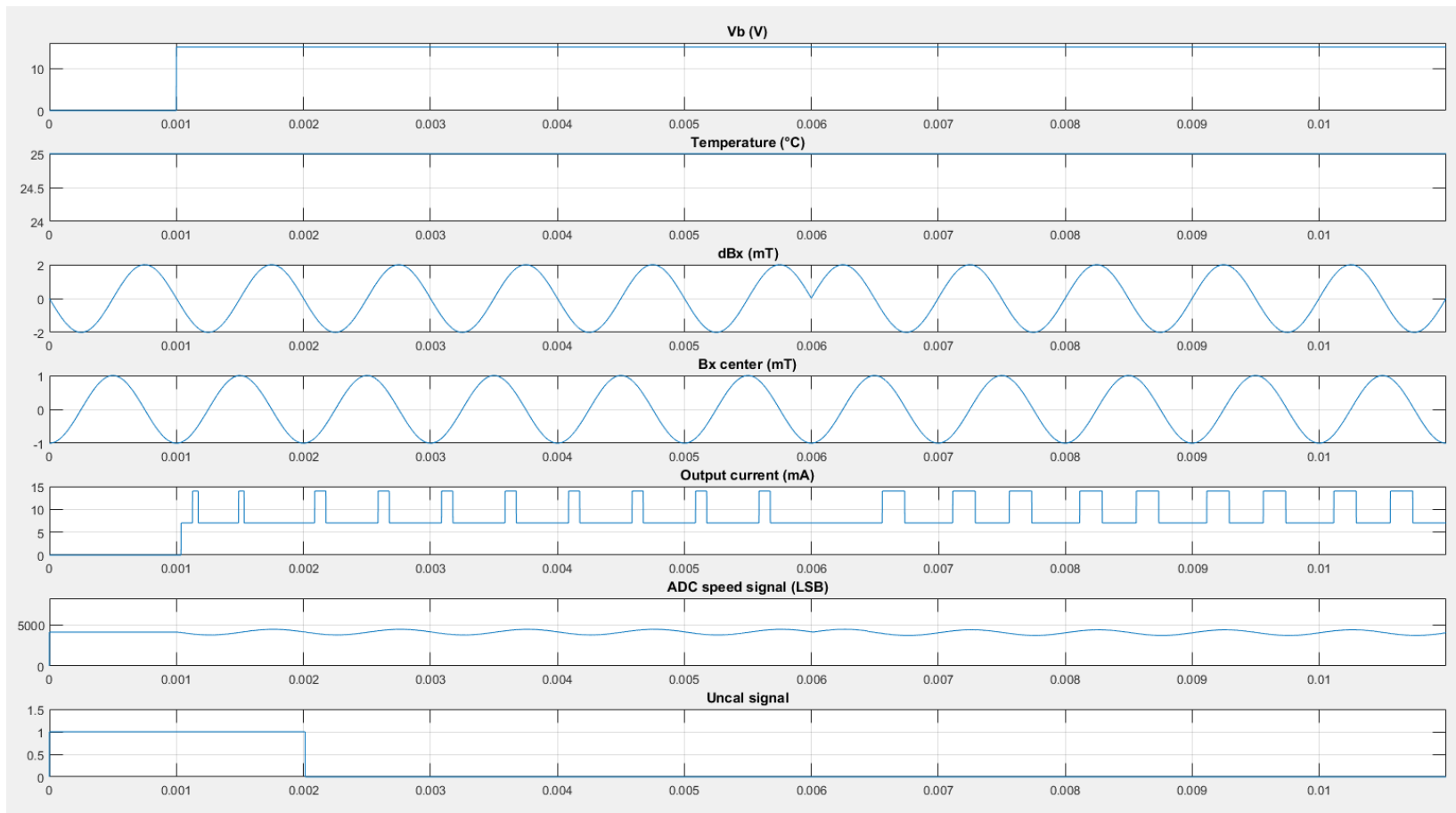


TLE5045iC/46iC models

Customer questions answered via simulations

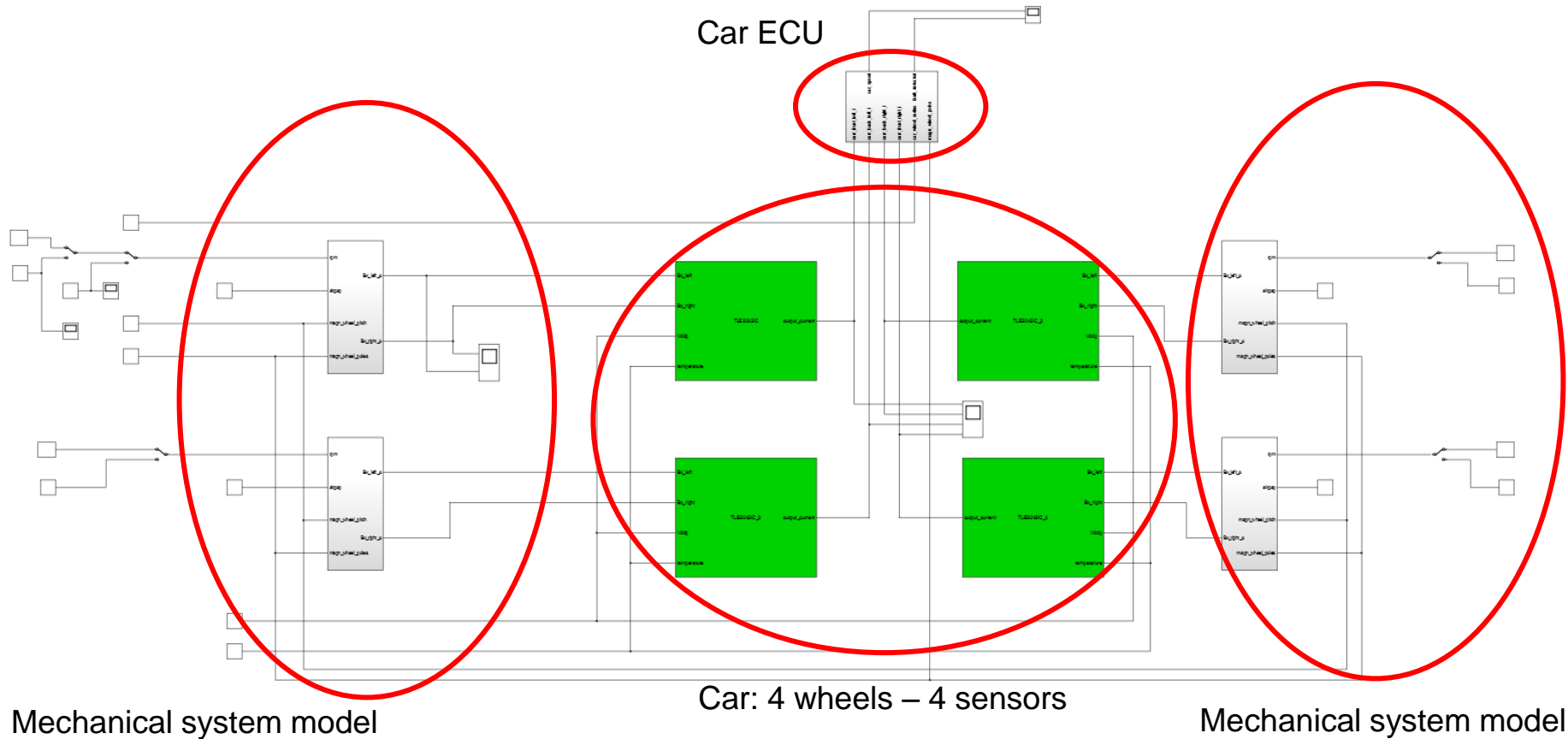


› Ex 2: Direction change of TLE5046iC-PWME



TLE5045iC/46iC models

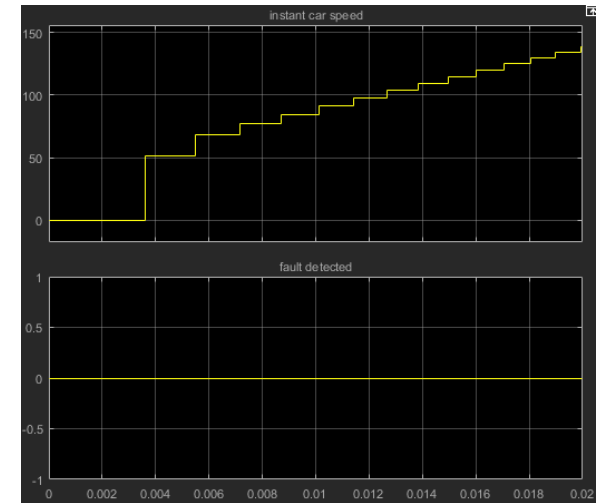
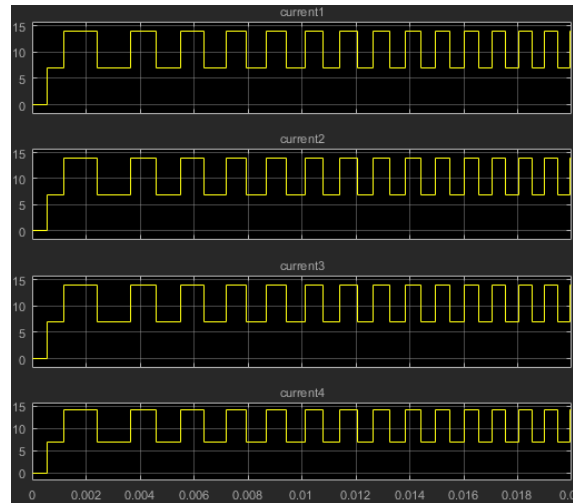
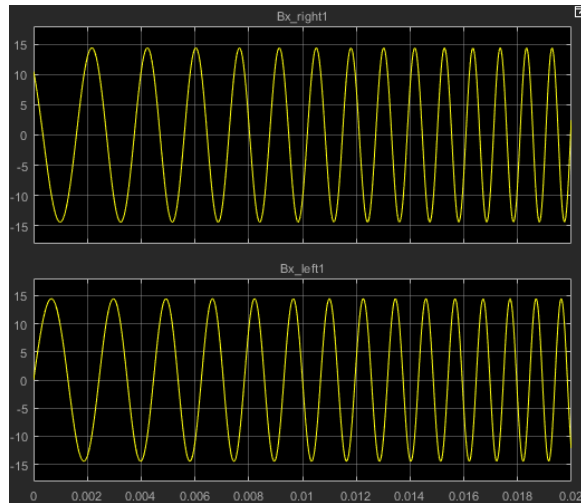
Product 2 System - Simulink demo (1/2)



TLE5045iC/46iC models

Product 2 System - Simulink demo (2/2)

1. Define the engine RPM and mechanical system
2. Observe the output current of the sensors
3. Calculate the car speed and detect malfunctioning



TLE5045iC/46iC models

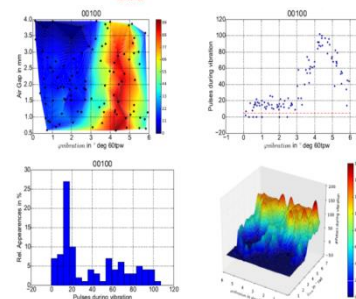
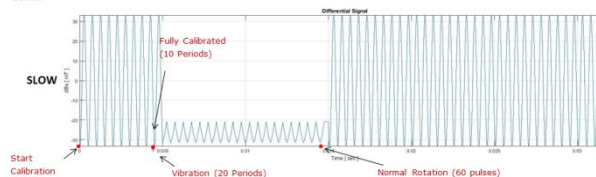
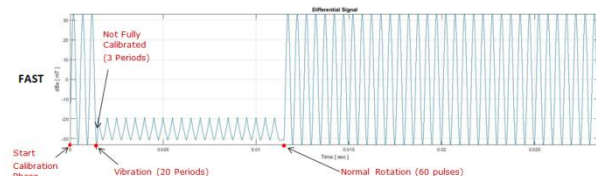
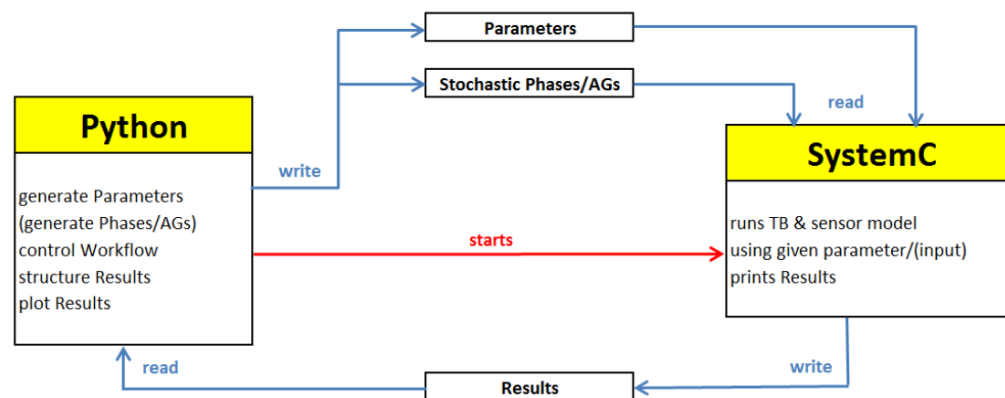
Root cause of complex behaviors



- › Accessibility to all internal signals
- › Worst case analysis easily made possible
- › Automatic checks via Matlab or SystemC
- › Understand the problem and THEN do specific measurements to obtain more accurate information
 - Cheaper
 - Faster

Speed sensors vibrations analysis

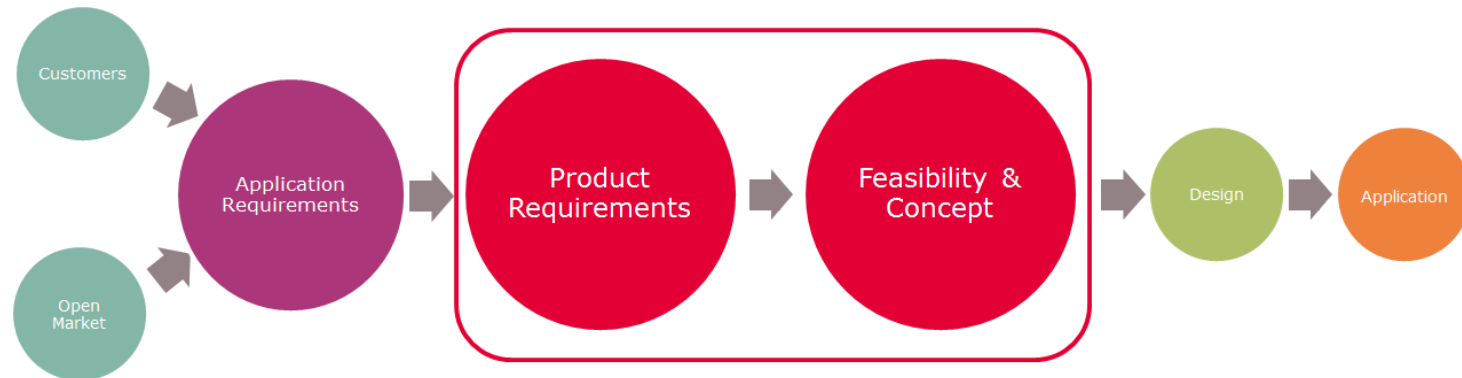
- › Systematic analysis on phase and airgap vibration behavior
 - Airgap
 - Starting phase
- › Iterative simulation and automatic post processing



C - Measurement @ 1.7mm										
Vibration phase Offset in deg@100 (0° is equal to one period)										
Amplitude	0	0.6	1.2	1.8	2.4	3	3.6	4.2	4.8	5.4
0.5	2	2	2	2	2	2	2	2	2	2
0.6	2	2	2	2	2	2	2	2	2	2
0.7	2	2	2	2	2	2	2	2	2	2
0.8	2	2	2	2	2	2	2	2	2	2
0.9	2	2	2	2	2	2	2	2	2	2
1.0	2	2	2	2	2	2	2	2	2	2
1.1	2	2	2	2	2	2	2	2	2	2
1.2	2	2	2	2	2	2	2	2	2	2
1.3	2	2	2	2	2	2	2	2	2	2
1.4	2	2	2	2	2	2	2	2	2	2
1.5	2	2	2	2	2	2	2	2	2	2
1.6	2	2	2	2	2	2	2	2	2	2
1.7	2	2	2	2	2	2	2	2	2	2
1.8	2	2	2	2	2	2	2	2	2	2
1.9	2	2	2	2	2	2	2	2	2	2
2.0	2	2	2	2	2	2	2	2	2	2
2.1	2	2	2	2	2	2	2	2	2	2
2.2	2	2	2	2	2	2	2	2	2	2
2.3	2	2	2	2	2	2	2	2	2	2
2.4	2	2	2	2	2	2	2	2	2	2
2.5	2	2	2	2	2	2	2	2	2	2
2.6	2	2	2	2	2	2	2	2	2	2
2.7	2	2	2	2	2	2	2	2	2	2
2.8	2	2	2	2	2	2	2	2	2	2
2.9	2	2	2	2	2	2	2	2	2	2
3.0	2	2	2	2	2	2	2	2	2	2

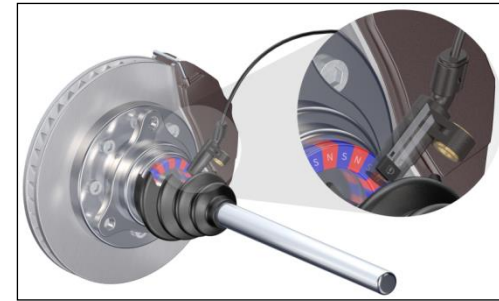
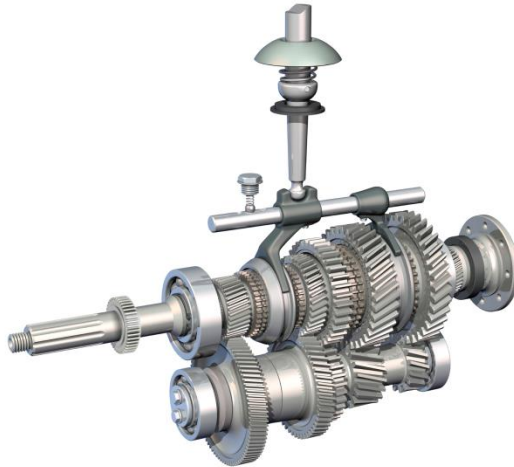
Current sensor

Product requirements & architecture definition



- › Model V1.0: Product Requirement Document
- › Model V2.0: Product Architecture and Safety Concept
- › Model V3.0: bit true version according to VHDL implementation

Speed sensors next generation

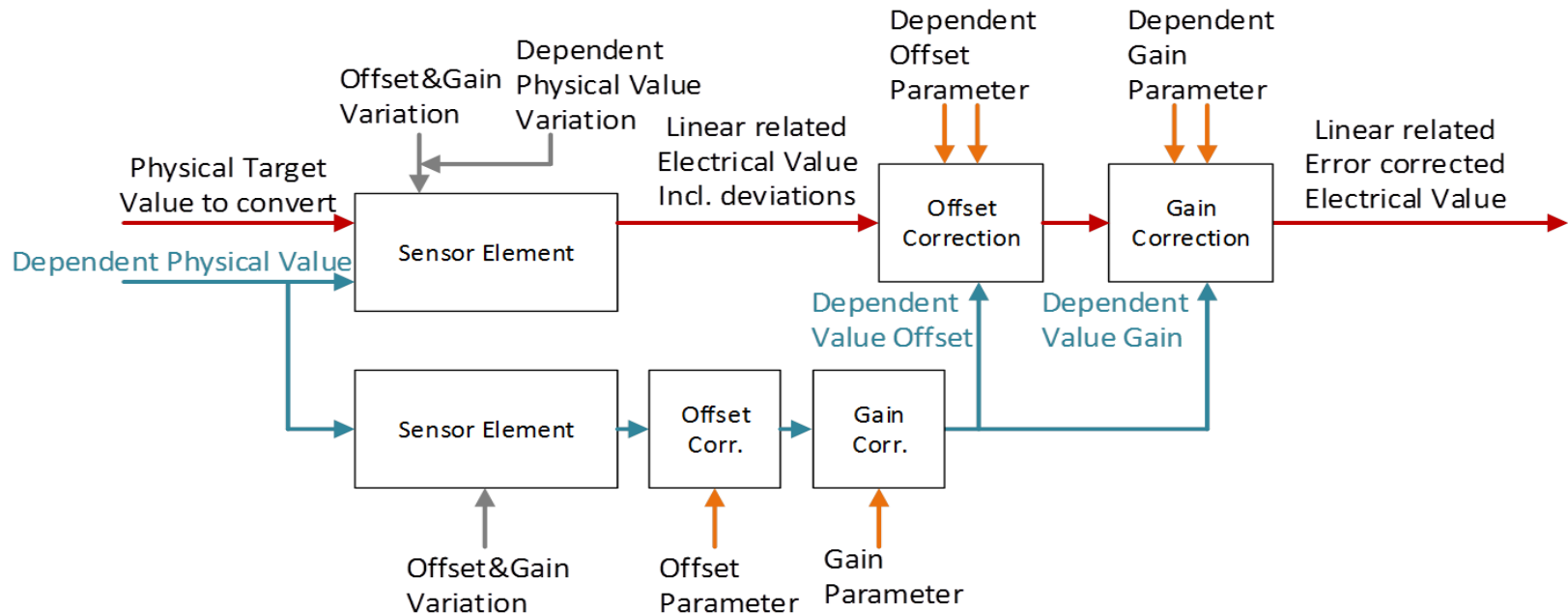


- › Transmission
- › ABS
- › Early feasibility study and concept definition
- › IP reuse from available product
 - Goal: LEGO like approach



Linear hall

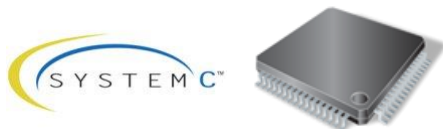
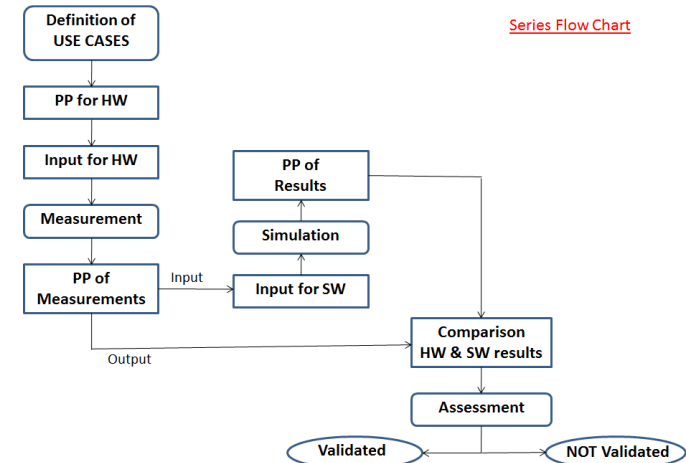
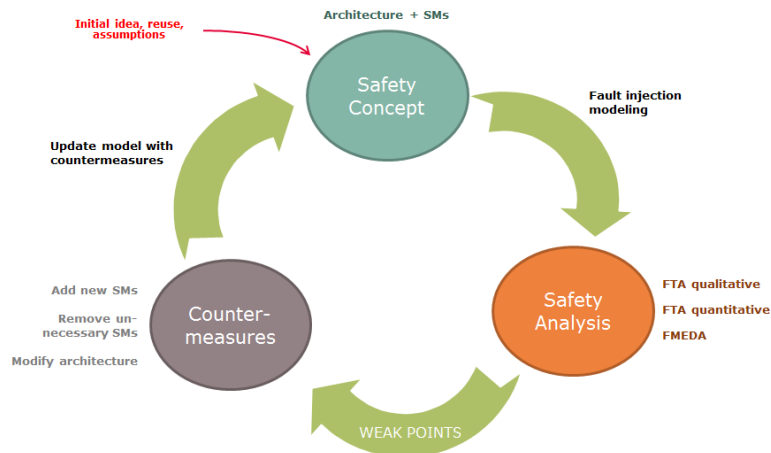
Data path modelling calibration



- › Goals for sensor data-path modeling
 - Data-path model for calibration and accuracy (stress & temperature)
 - Derivation of module requirements
 - Executable specification for implementation

Ongoing & planned: HW co-verification, SysC fault injection, FPGA

- › Fault injection on SystemC modeling
- › Co-verification with HW
- › FPGA prototyping (SysC → VHDL)



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Conclusions

Why do we like Coside?

- › Eclipse-based IDE
 - Easy to learn
 - Most of the students already used to it @ Uni
- › GUI & Schematic
 - Helpful for hierarchic design & architecture definition
- › XML interface to create fast .h and .cpp
 - Focus on the funnier part 😊
- › Simulations utilities
 - Tb automatic generation
 - Schematic view with primitives available

Why do we like Coseda?

- › Effective and fast support, very competent and helpful people



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> Use cases

- Customer design-in
- Executable specs
- Requirements validation
- Virtual prototyping
- Architecture exploration
- Design reference
- Integration validation

> Advantages

- Early system verification and system concept development for the customers
- First PRQ validation
- Improve PRQ quality
- Save costs and improve time-to-market
- Early product verification dev.
- Test-benchs created for model verification can be reused for product verification

- **Behavioral modeling is a powerful tool for development and design-in activities and both the customers and Infineon can highly benefit from it.**
- **Coside plays a fundamental role in our SystemC development flow.**